

The Bayesian Analysis Toolkit

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Introduction

BAT → Software package for solving of statistical problems using Bayesian approach

Bayes' formula for parameter estimation

$$p(\vec{\lambda} \mid \vec{D}) = \frac{p(\vec{D} \mid \vec{\lambda}) p_0(\vec{\lambda})}{\int p(\vec{D} \mid \vec{\lambda}) p_0(\vec{\lambda}) d\vec{\lambda}}$$

Motivation:

- many of us have done Bayesian analyses in HEP always having to implement the numerical
 algorithms and tools by ourselves → generally non-trivial
- create a package/toolkit to take care of that

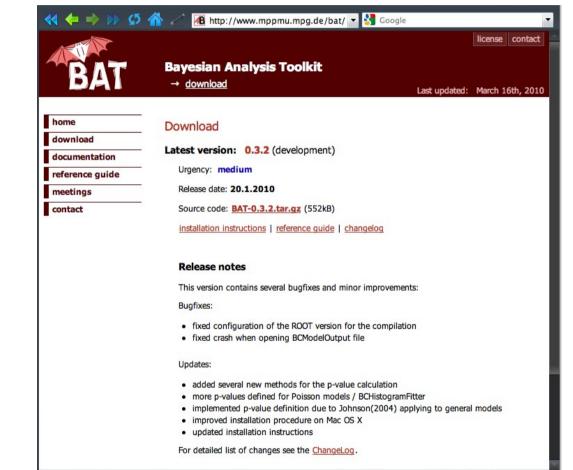
The idea behind BAT

- Merge common parts of every Bayesian analysis into a software package
- Provide flexible environment to phrase arbitrary problems
- Provide a set of well tested/tuned numerical algorithms and tools
- C++ based framework (flexible, modular)
- Interfaces to ROOT, Cuba, Minuit, user defined, ...



BAT availability

- can be downloaded from: <u>http://www.mppmu.mpg.de/bat</u>
- BAT comes in form of shared library
- depends of the ROOT I/O functionality
- BAT contains at the moment 15 classes which provide:
 - main infrastructure
 - algorithms
 - output and logging
 - extension classes to solve specific (frequent) fitting problems
- a set of well documented examples is included in BAT distribution
 - good starting point
- "Introduction to BAT" document



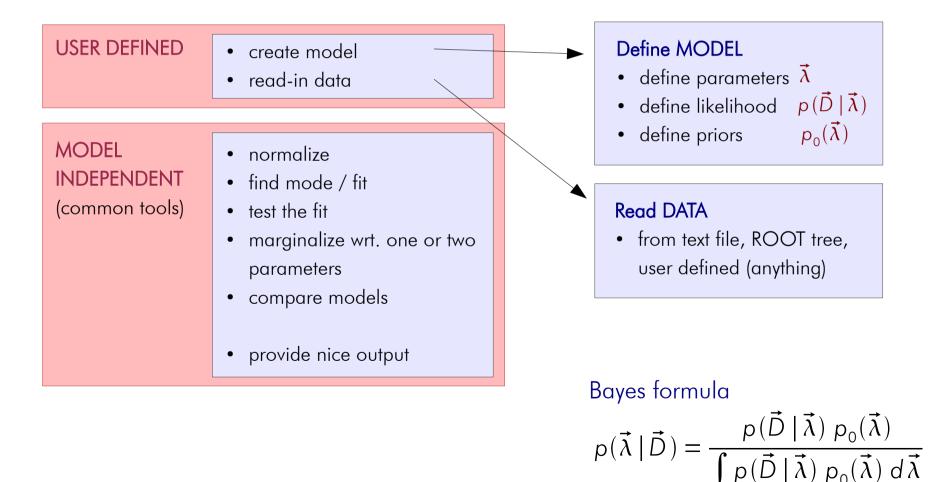
• the BAT paper: Computer Physics Communications 180 (2009) 2197-2209



The idea

Separate the common parts from the rest

- case specific: the model and the data
- common tools: all the rest





- Posterior mapping \rightarrow Marginalization
 - Markov Chain Monte Carlo (MCMC)
 - key tool in the package
 - lot of emphasis put on efficiency, performance and validation
- Integration
 - Monte Carlo (sampled mean), Cuba (Vegas, ...)
- Maximization
 - Monte Carlo, MCMC, Minuit, Simulated Annealing
- Model testing
 - Posterior comparison, K-factors, p-value calculation
- User interface
 - simple model definition
 - standard output: text output, plots, ROOT histograms and trees, ...



 $p(\lambda_i \mid \vec{D}) = \int p(\vec{D} \mid \vec{\lambda}) p_0(\vec{\lambda}) d\vec{\lambda}_{i \neq i}$

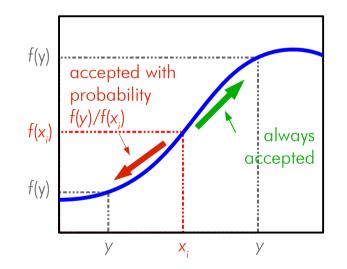
- generally it is very difficult to obtain the full posterior PDF
 - number of parameters can be large
 - different input data will result in a different posterior
- also the visualization of the PDF in more than 3 dimensions is rather impractical and hard to understand
- usually one looks at marginalized posterior wrt. one, two or three parameters
 - a projection of the posterior onto one (two, three) parameter
 - integrating all the other parameters out

still numerically difficult

- the Markov Chain Monte Carlo revolutionized the area of Bayesian analysis
 - Metropolis algorithm



- In BAT implemented Metropolis algorithm
- Map positive function f(x) by random walk towards higher probabilities
- Algorithm:
 - Start at some randomly chosen x_i
 - Randomly generate y around x_i
 - If $f(y) \ge f(x_i)$, set $x_{i+1} = y$
 - If $f(y) < f(x_i)$, set $x_{i+1} = y$ with probability $p = \frac{f(y)}{f(x_i)}$
 - If y not accepted, stay where you are, i.e., set $x_{i+1} = x_i$
 - Start over



- For each step fill the histogram with x_{i+1}
- For infinite number of steps the distribution in the histogram converges to *f(x)* except for the normalization

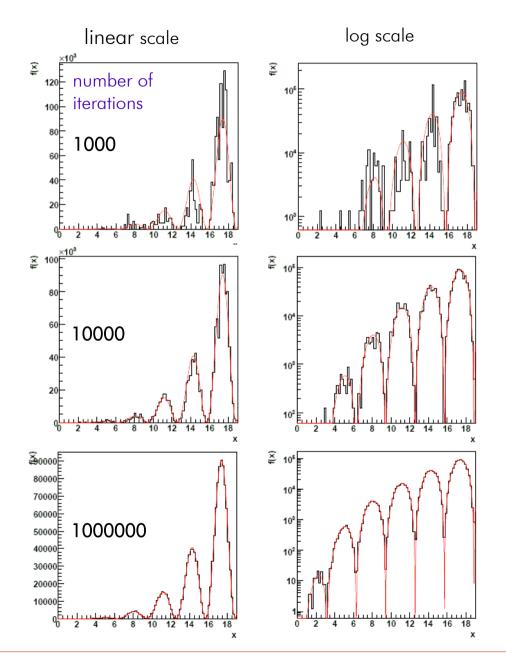


MCMC: an example

- mapping an arbitrary function: $f(x) = x^4 \sin^2 x$
- distribution sampled by MCMC in this case quickly converges towards the underlying distribution
- mapping of complicated shapes with multiple minima and maxima

Note:

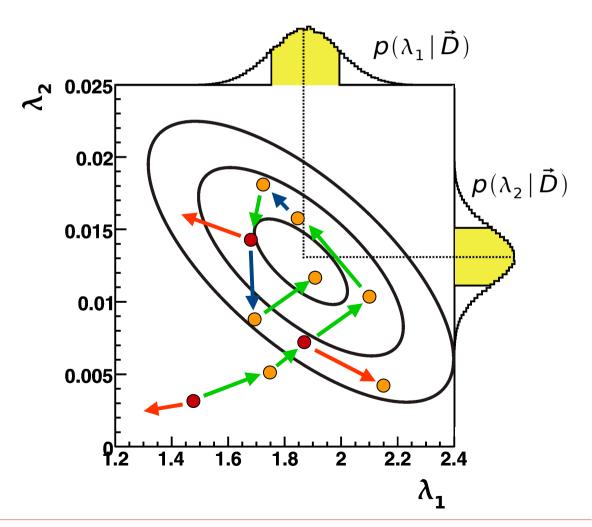
- MCMC has to become stationary to sample from underlying distribution
- in general the convergence is a nontrivial problem





- In Bayesian analysis use MCMC to scan parameter space of $\vec{\lambda}$
- $f(\vec{\lambda}) = p(\vec{D} \mid \vec{\lambda}) p_0(\vec{\lambda})$
- MCMC converges towards underlying distribution
 - Determining of the overall probability distribution of the parameters $p(\vec{\lambda} \mid \vec{D})$
- Marginalize wrt. individual parameters while walking
 → obtain
 p(λ_i | D
) = ∫ p(D
 | λ
) p₀(λ) d λ
 _{j≠i}
- Find maximum (mode)
- Uncertainty propagation

$$p(\vec{\lambda} \mid \vec{D}) = \frac{p(\vec{D} \mid \vec{\lambda}) p_0(\vec{\lambda})}{\int p(\vec{D} \mid \vec{\lambda}) p_0(\vec{\lambda}) d\vec{\lambda}}$$





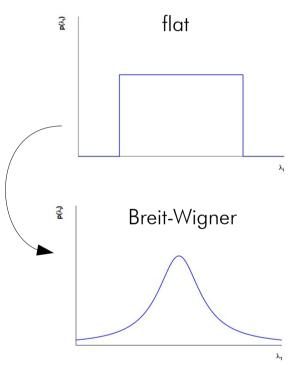
Running several chains in parallel (default is 5)

- Start at random locations in allowed parameter space
- Initialize chains by doing a pre-run to achieve convergence
 - Convergence defined using r-value (Gelman & Rubin, StatSci 7, 1992)
 - Essentially a ratio of the mean of the variances and the variance of the mean values of the chains for each parameter
 - Convergence criterion |*r*-1| < 0.1
- Steps in parameter space done consecutively for each parameter and chain
- Proposal function for new steps is a product of Breit-Wigner functions with varying widths
- The efficiency for accepting new point is evaluated for each parameter and chain over last min(npar*1000,10000) iterations and the widths are adjusted for all parameters to increase the performance
 - If efficiency > 50%, increase the width
 - If efficiency < 15%, decrease the width
- use MCMC only after pre-run has ended, convergence was reached and all parameter proposal widths have been adjusted

Most parameters can be set by the user

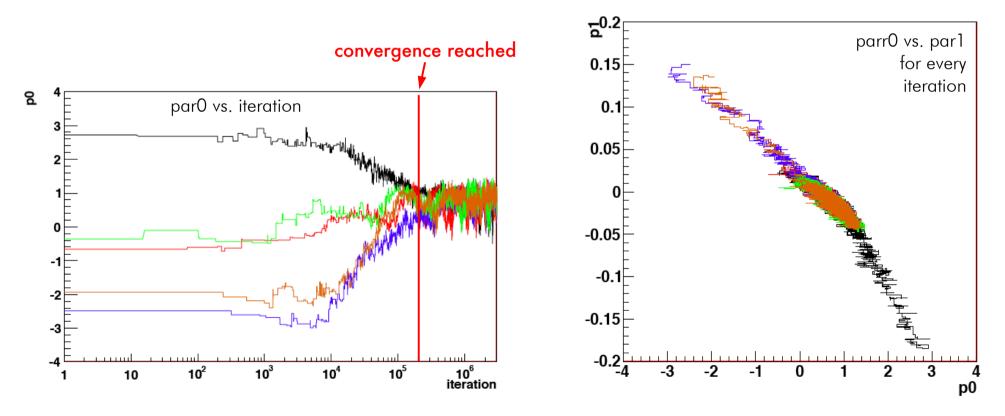


- by default using independent proposal functions for each parameter, i.e., new MCMC point for each parameter generated separately
- tested several different proposal functions on multi-peak distributions with deep valleys of probability density between them
 - old default: flat distribution
 - adjusting step size to achieve high efficiency
 - convergence problems
 - new default: Breit-Wigner distribution
 - adjusting width to achieve high efficiency
 - best convergence performance on all tested examples
 - Gaussian distribution
 - tails too low, convergence not very good
- it is possible to overload the proposal function with user defined function
 - either separately for every parameter
 - or with a single correlated function



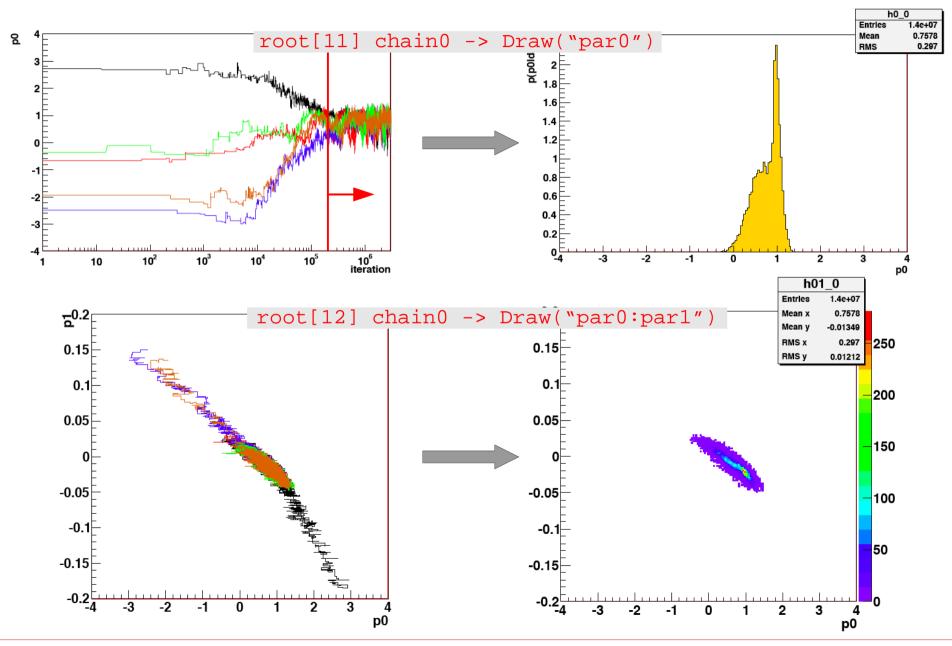


- danger of non-convergence still remains
- the full chain(s) can be stored for further analysis and parameter tuning as ROOT TTree(s)
 - allows direct usage of standard ROOT tools for analysis
- Markov Chain contains the complete information about the posterior (except for the normalization)



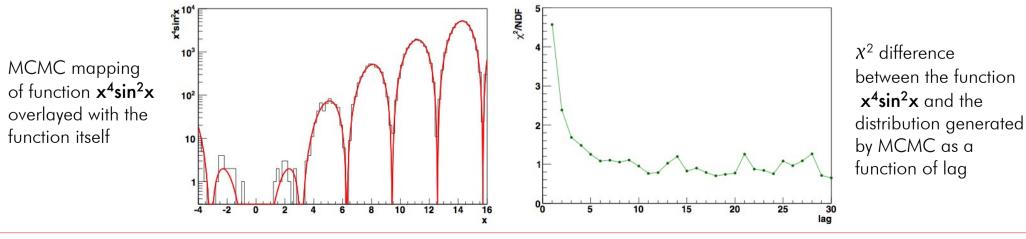


Obtaining marginalized distributions from TTree





- due to sampling nature of the MCMC, there is an autocorrelation between samples
 - newly generated point to some extent depends on the previous point, especially if stepsize/range for generating new point is small
 - autocorrelation can be removed by "thinning" the sample introducing a lag N
 - only every N-th sample from MCMC is used to generate the distribution
 - cost for better description of the mapped PDF is high number of iterations has to be increased by factor N to reach the same statistical power
 - lag can be set in BAT (default is 1, i.e., no lag)
 - all calculations and filling of the distributions are only performed every N-th iteration
 - testing on various distributions shows improved MCMC description when using lag





What's done within one run of the MCMC in BAT?

- for every iteration the histograms for all 1D and 2D marginalized distributions are filled (TH1Ds and TH2Ds)
 - large number of histograms: Nparam (Nparam+1) / 2
 (e.g. for Nparam=50 there are 1275 histograms in total)
 - it is possible to switch off filling of individual distributions
- any function of parameters can be evaluated for every iteration
 - most natural candidate is uncertainty propagation
- since we're scanning parameter space, location of maximum can be found
 - not very efficient for maximization (minimization)
 - mode found in MCMC is generally an excellent starting point for other minimization algorithms
 - Minuit or Simulated Annealing can be used directly from BAT

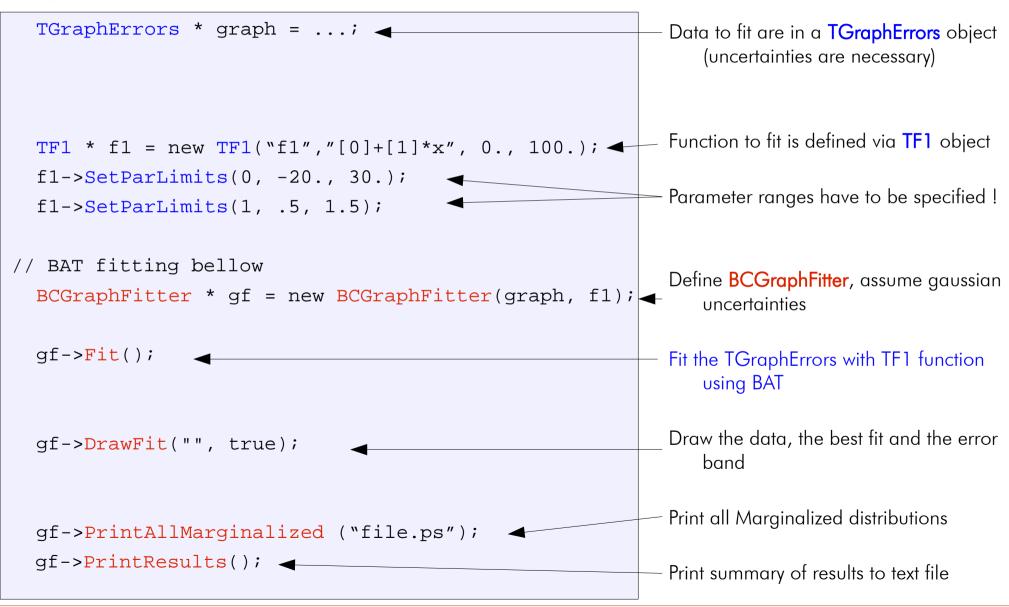


- BAT analysis can be run in compiled mode as well as from within an interactive ROOT session (ROOT macro)
 - examples distributed together with BAT show both types of use
- user model is defined by creating a model class that inherits from the base model class
 BCModel
 - define parameters and their ranges
 - define the LogLikelihood() method
 - define the LogAPrioriProbability() method
- in the main program use the functionality of BCModel to perform the analysis
- script CreateProject.sh from the BAT distribution creates several source files with a skeleton
 of a new model definition, main program and an appropriate Makefile
- in addition, several predefined models in BAT remove the need to define a model for frequent analysis problems: Fast fitters



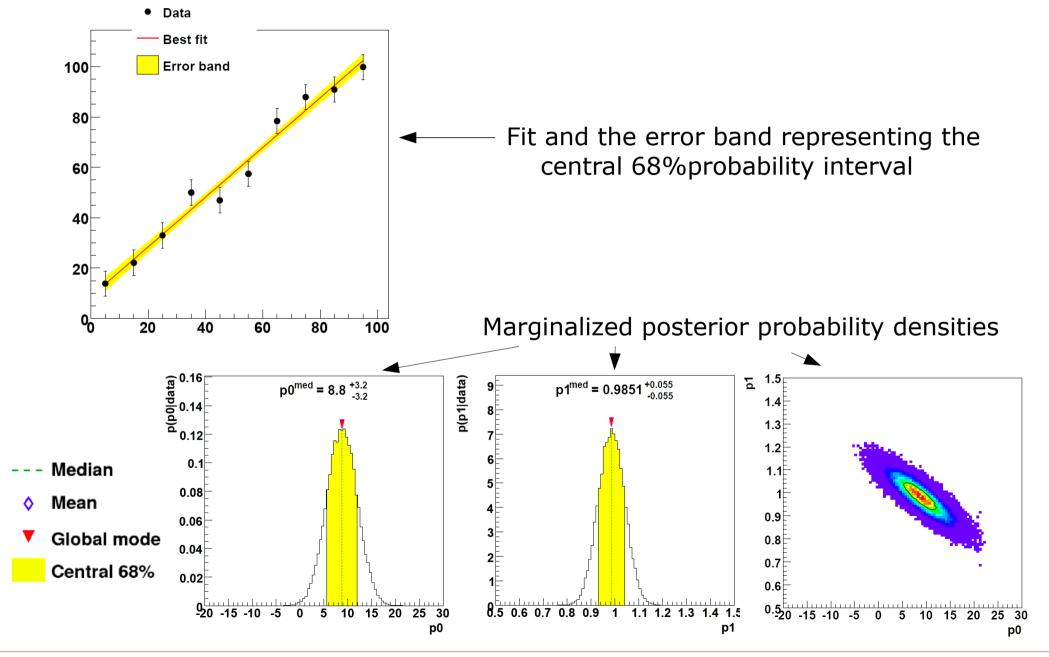
Simple GraphFitter example

Simple ROOT macro:





Graphical output





results.txt

Summary

Model summary

-----Model: GraphFitter with f1 Number of parameters: 2 List of Parameters and ranges: (0) Parameter "p0": (-20, 30) (1) Parameter "p1": (0.5, 1.5)

Results of the marginalization

List of parameters and properties of the marginalized distributions:

(0) Parameter "p0":	
Mean +- sqrt(V):	8.756 +- 3.152
Median +- central 68% interval: 8.77 + 3.115 - 3.138	
(Marginalized) mode:	8.75
5% quantile:	3.519
10% quantile:	4.693
16% quantile:	5.632
84% quantile:	12.01
90% quantile:	12.77
95% quantile:	13.91
Smallest interval(s) containing 68% and local modes:	
(5.5, 12.5) (local mode at 8.75 with rel. height 1; rel. area 0.7)	
(1) Parameter "p1":	

. . .

Results of the optimization

_____ Optimization algorithm used: Minuit List of parameters and global mode: (0) Parameter "p0": 8.779 +- 3.165 (1) Parameter "p1": 0.9847 +- 0.05493

Results of the model test

------p-value at global mode: 0.6913

Status of the MCMC

Convergence reached: yes Number of iterations until convergence: 6001 Number of chains: 5 Number of iterations per chain: 100000 Average efficiencies: (0) Parameter "p0": 22.62% (1) Parameter "p1": 20.22%

Notation:

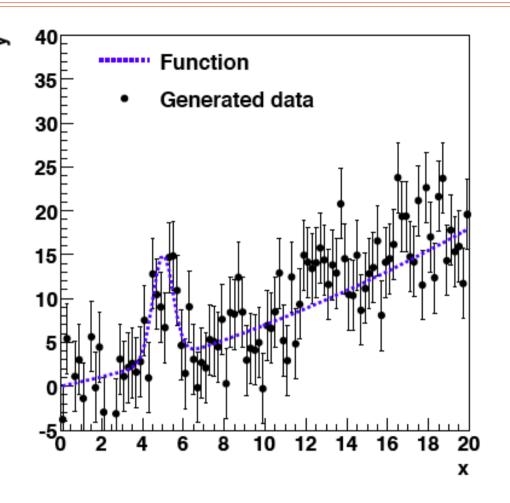
: mean value of the marg. pdf Mean : maximum of the marg. pdf Median Marg. mode : most probable value of the marg. pdf : Variance of the marg. pdf V Quantiles : most commonly used quantiles

. . .



Another GraphFitter example

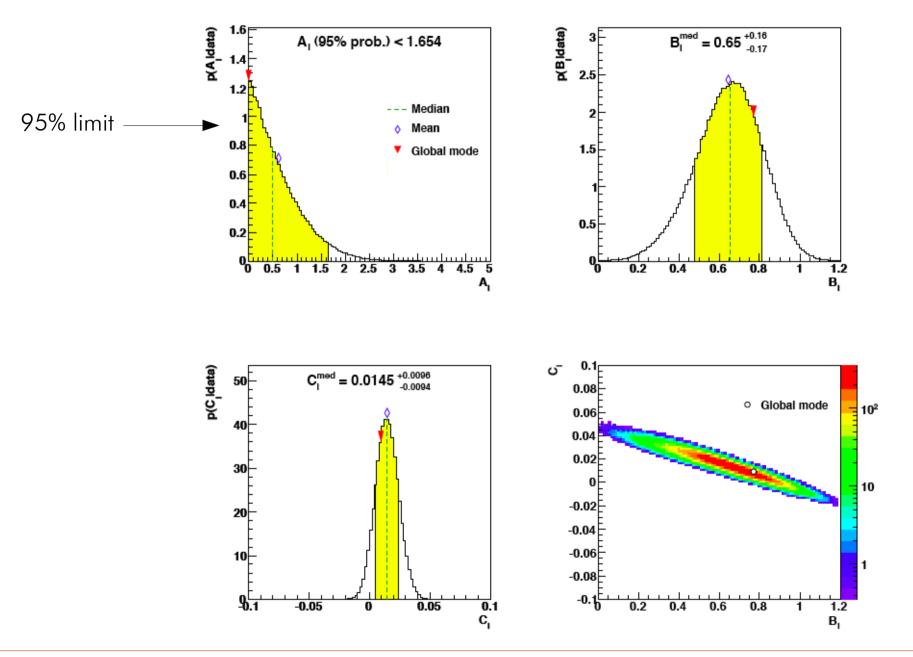
- Fit data set using:
 - I. 2nd order polynomial (no peak)
 - II. gaussian peak + constant
 - III. gaussian peak + straight line
 - IV. gaussian peak + 2nd order pol.



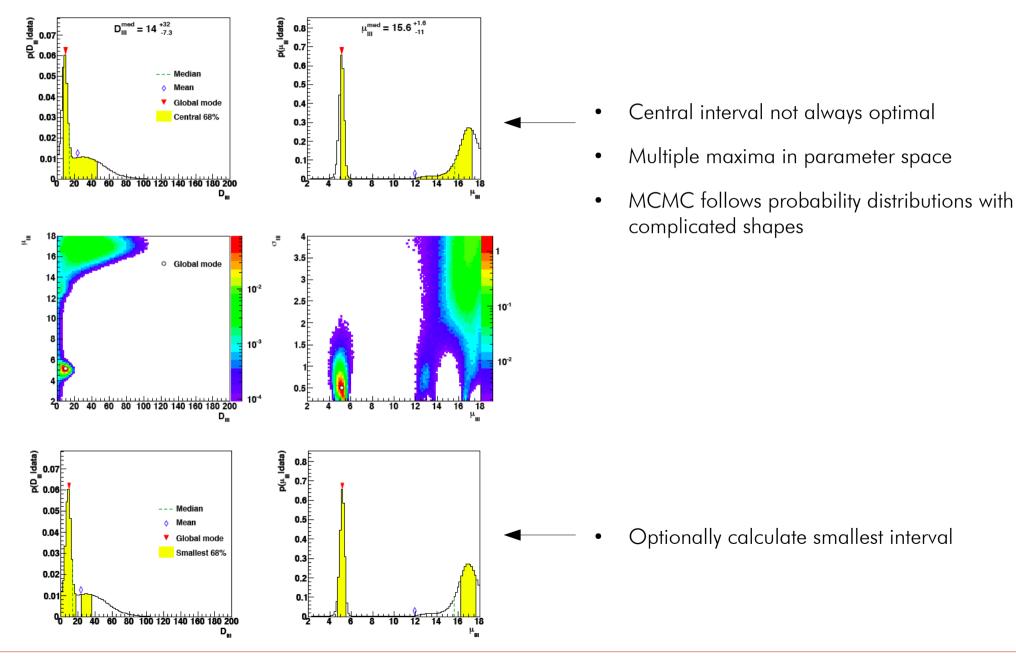
- Assume flat a priori probabilities in certain ranges of parameters, i.e. $p_0(\vec{\lambda}) = \text{const.}$
- Search for peak in range from 2. to 18. with maximum sigma of 4.
- Data were generated as gaussian peak + 2nd order polynomial



Marginalized posterior pdf 2nd order polynomial



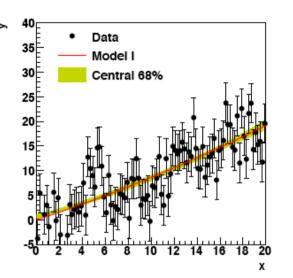


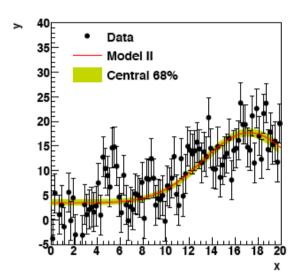


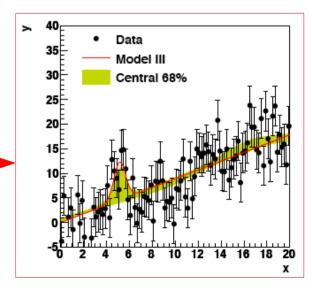


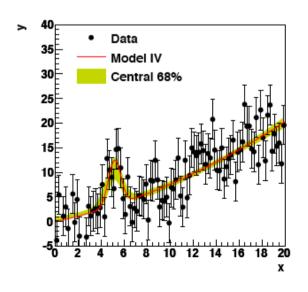
Fits + Uncertainty bands

- Uncertainty band calculated during Markov Chain run
 - calculate f(x) at many different
 x using λ sampled according
 to posterior
 - fill 2D histogram in (x,y)
 - after run look at distribution of y at given x and calculate central 68% interval
- Fit can lie outside of the central 68% interval
- Again, for multimodal distributions central 68% not
 optimal



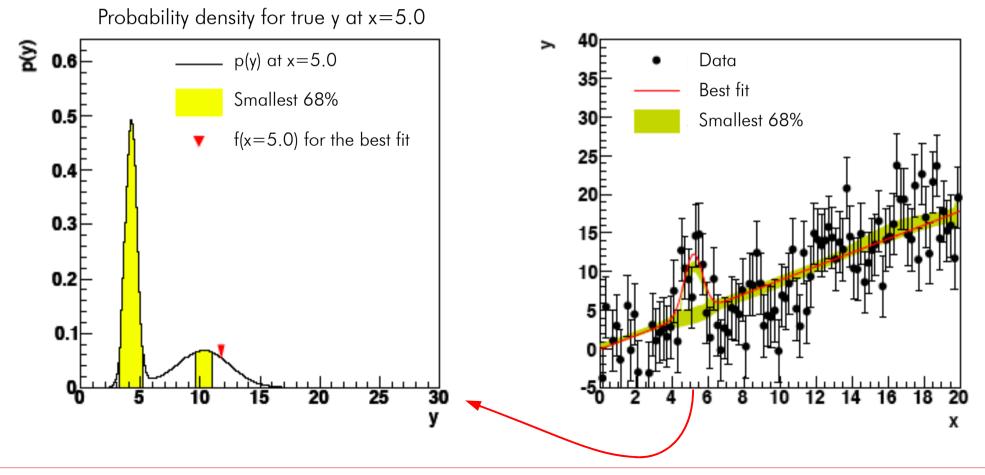








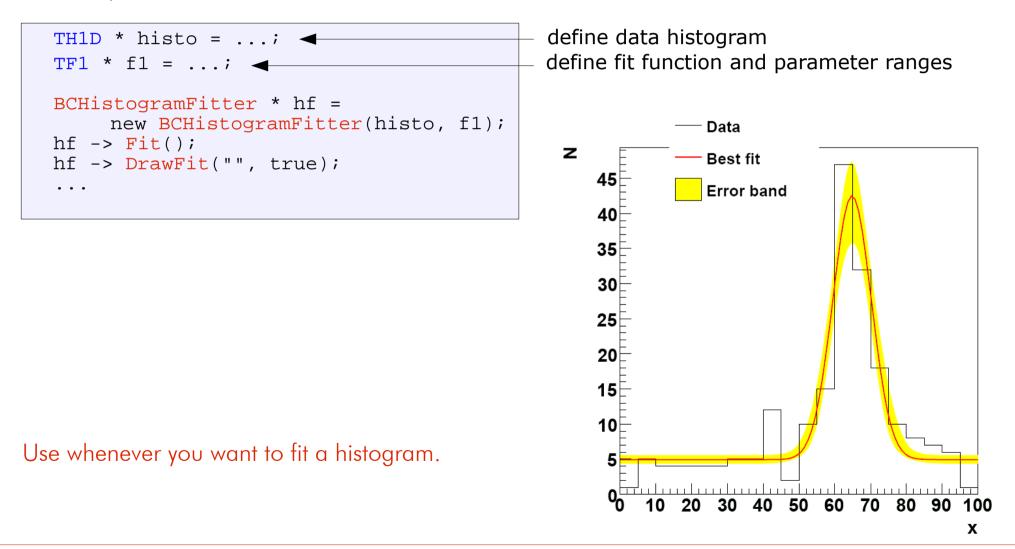
- Calculating f(x) at many x for every set of parameters sampled in the Markov chain ⇔ uncertainty propagation
- Can lead to multiple uncertainty bands





Simple ROOT macro:

- takes histogram as an input
- uses poissonian uncertainties

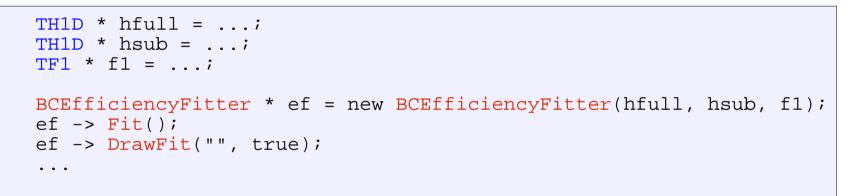


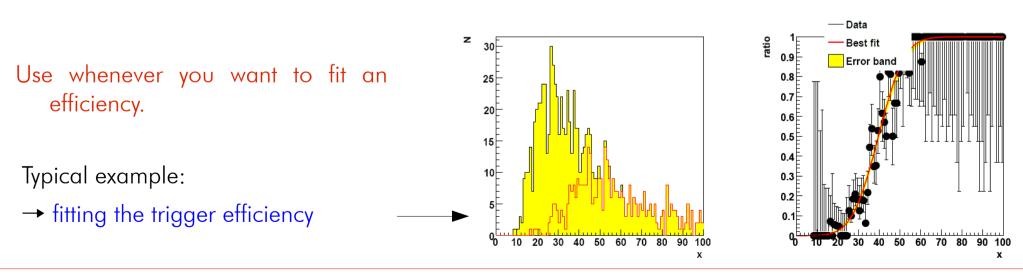


EfficiencyFitter example

Simple ROOT macro:

- takes two histograms as an input:
 - histogram with the whole set of events/entries
 - histogram with subset of events/entries
- uses binomial uncertainties

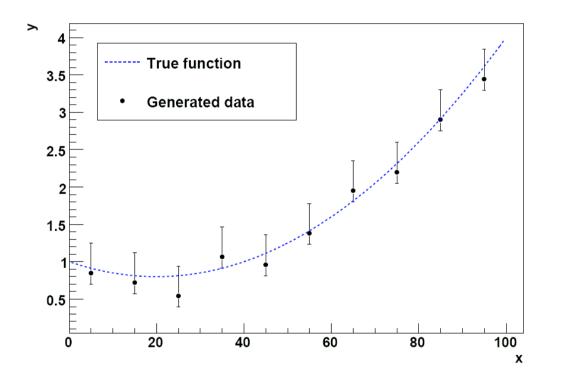




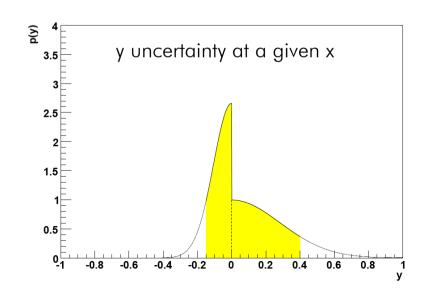


- by default the priors for all parameters are flat !
 - to set a different than flat prior one has to at the moment create a new class which inherits from a fast fitter class and overload the LogAPrioriProbability() method
 - in the next release it will be possible to set a prior for individual parameter as a TF1 object
- all fast fitters inherit from BCModel so they can use all it's functionality to also do a more sophisticated analysis
 - normalize
 - compare models
 - use fancy plotting
 - ...





- Data generated according to 2nd order polynomial
- Fit using straight line and 2nd order polynomial
- assuming 2 half gaussians for the description of the asymmetric errors
- JUST TO ILLUSTRATE THE MODEL
 DEFINITION!





```
USER MODEL EXAMPLE - 2nd order polynomial (model class)
```

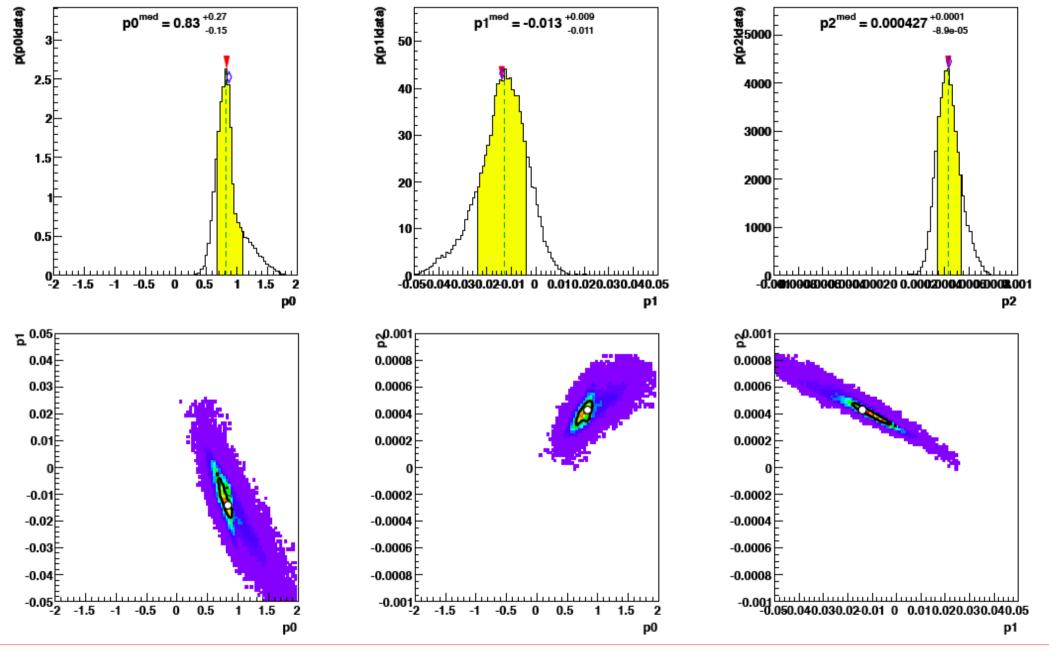
```
void ModelPol2::DefineParameters() { // define parameters of the model
  this -> AddParameter("A", 0., 5.); // index 0
  this -> AddParameter("B", 0., 1.2); // index 1
  this -> AddParameter("C", -0.1., 0.1); // index 2
                                           // fit function is f(x) = A + Bx + Cx^2
}
double ModelPol2::LogLikelihood(vector <double> params) { // define likelihood
  double lprob = 0.;
  double A = params[0], B = params[1], C = params[2];
  for(int i=0; i<this -> GetNDataPoints(); i++) { // loop over all data points
     BCDataPoint * data = this -> GetDataPoint(i);
     double
                   x = data \rightarrow GetValue(0):
                  y = data -> GetValue(1);
     double
     double yerrdown = data -> GetValue(2); // asymmetric errors on all points
     double verrup = data -> GetValue(3);
     double yexp = A + x^*B + x^*x^*C; // calculate expectation value
                    = (y>yexp) ? yerrdown : yerrup; // decide which uncertainty is applicable
     double verr
     lprob += BCMath::LogGaus(y, yexp, yerr, true);
  }
  return lprob;
}
double ModelPol2::LogAPrioriProbability(vector <double> params) { // define prior
  return 0.; // flat prior probability for all parameters in their range; !!! not normalized !!!
}
```



```
USER MODEL EXAMPLE - 2nd order polynomial (simple main program)
int main()
{
   ModelPol2 * mymodel = new ModelPol2("2Dpol"); // create model object
   DataSet * mydata = new DataSet("measurement1"); // create data object
   mydata->ReadDataFromFileTxT("measurement1.dat",4); // read in data, 4 columns: x,y,erup,erdn
   mymodel->SetDataSet(mydata); // assign data to model
   // mymodel->Normalize(); // integrate to get the normalization
   mymodel->MarginalizeAll(); // marginalization
   mymodel->PrintAllMarginalized("mymodel all.ps");
   mymodel->FindModeMinuit( mymodel -> GetBestFitParameters() ); // Mode finding using Minuit
   BCModelOutput * myout = new BCModelOutput(mymodel, "mymodel.root");
   myout->WriteMarginalizedDistributions();
   myout->WriteErrorBand();
   myout->Close();
   mymodel->PrintResults();
   // add more things to do
   return 0;
}
```



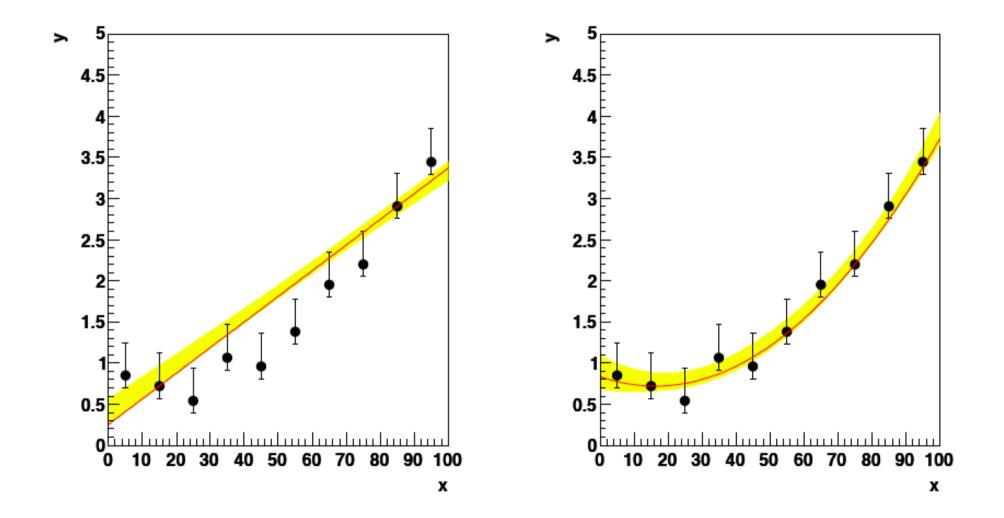
1D and 2D marginalized distributions







Example with asymmetric errors Fit + error band





- class **BCRooInterface** implemented by Gregory Schott from RooStats team
 - no MCMC available in RooStats at that time
- allows to run complete BAT analysis starting from RooFit workspace
 - contains definitions of parameters and their ranges, likelihood, prior, data
 - full definition of a model in BAT
- work is ongoing on implementation of a complete interface to RooStats
 - allowing to call BAT from within RooStats during run-time
 - providing results in RooStats format
 - more or less transparent for RooStats users



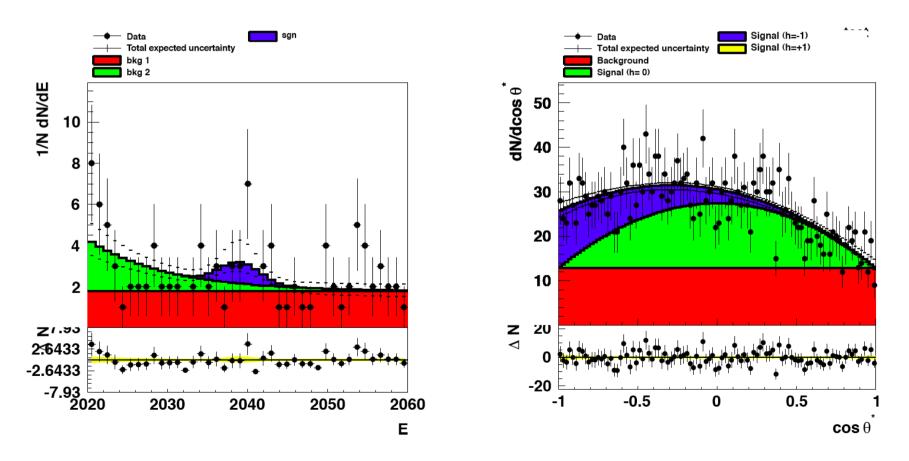
Next BAT release

- current BAT version is 0.3.2
- next version 0.4 to show up within several weeks
 - many updates planned
 - easy setup of priors without need of overloading LogAPrioriProbability() (especially useful for fast fitters)
 - new fast fitter class TemplateFitter
 - new tool to provide better summary of results
 - some performance improvements
 - ...



Template Fitter

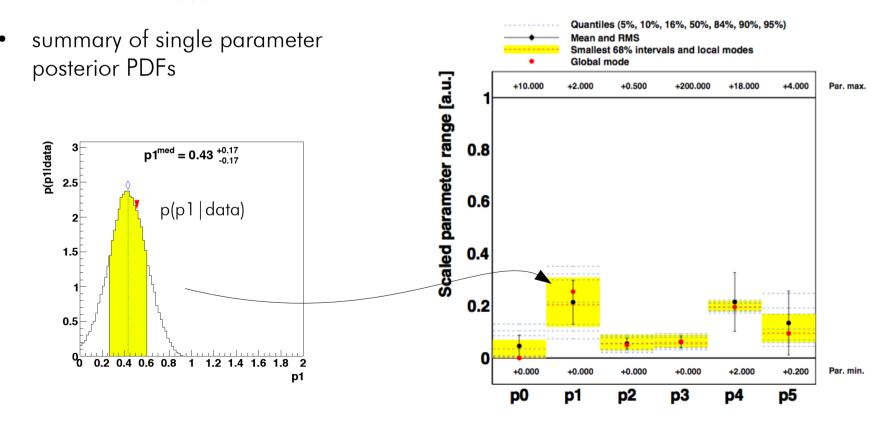
- fit a set of templates to a histogram
 - e.g. a signal peak on top of a multi-component background
 - assuming that the shapes of all components are known
 - estimate the size of all contributions





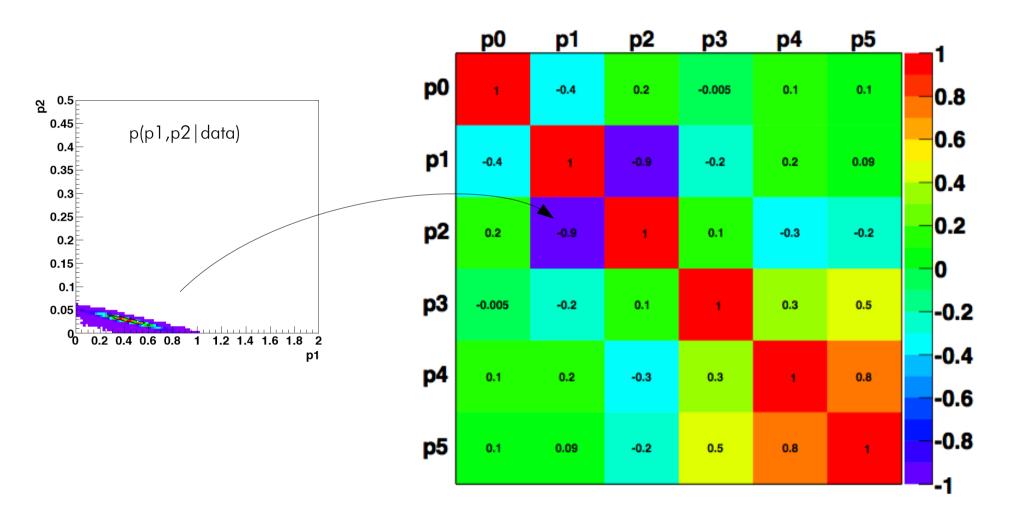
- tool providing summary plots for easy overview of results without having to go through all the plots of marginalized distributions
 - particularly useful for models with large number of parameters

```
• easy to use: SummaryTool * summaryM1 = new SummaryTool();
summaryM1->SetModel(model1);
summaryM1->PrintParameterPlot("par_M1.eps");
summaryM1->PrintCorrelationPlot("corr_M1.eps");
```





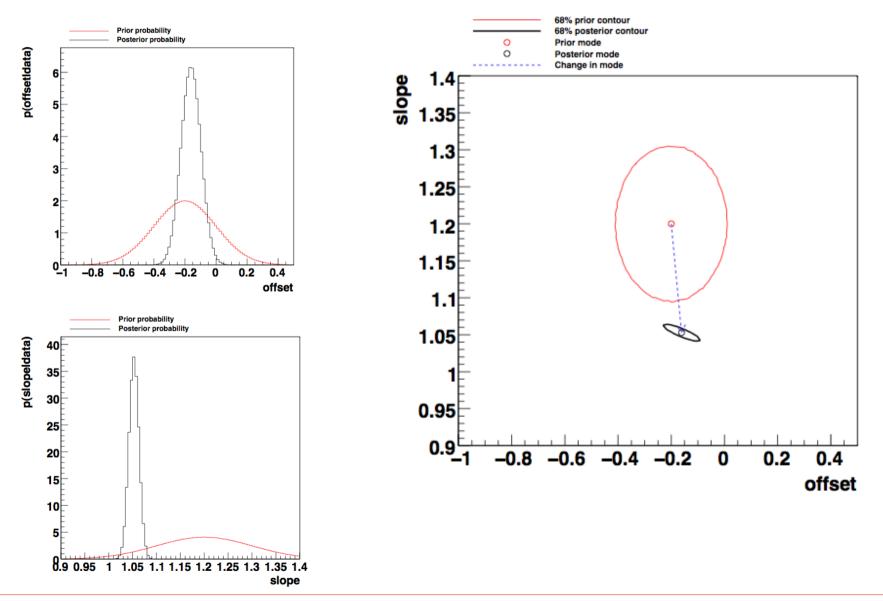
• summarizes Npar*(Npar-1)/2 posterior distributions marginalized wrt. combination of any two parameters of the model (for Npar=50 it's \sim 1000 distributions) into a single plot





SummaryTool – Knowledge update

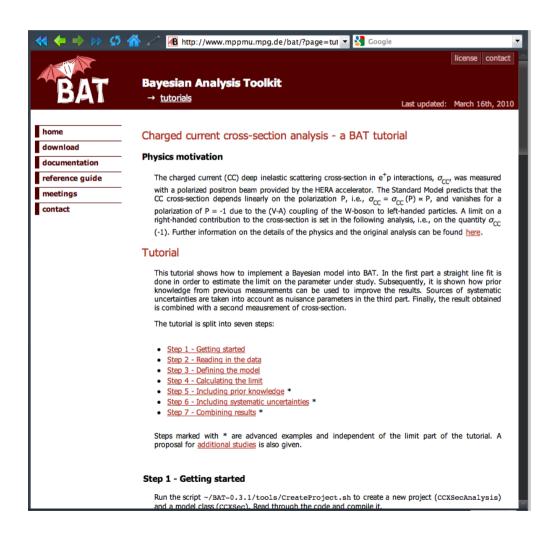
• comparison of prior and posterior for 1D and 2D distributions





Tutorials

- tutorials section was recently added to the BAT webpage
 - can be found under: Documentation → Tutorials
- several tutorials available
- show basic information on how to
 - set up a model
 - calculate limits
 - define prior
 - include systematic uncertainties
 - etc.
- tutorials have form of exercises with solutions
- more tutorials will come





- we're starting to be limited by the current structure of the code especially when trying to implement new algorithms
 - we're preparing reworked BAT with new internal structure which should allow much easier extensibility
 - slowed down by the required maintenance of the current BAT + user requests
 - not too much manpower until now, but this will change soon
- many things to implement
 - objective priors, reference priors
 - different sampling algorithms
 - extended proposal functions
- more predefined models for frequent problems for quick use
- feature requests are accepted
 - you can also contribute yourself
 - if you make an analysis using BAT and it's addressing a general problem, it might be worth to consider making it available as a predefined class for easy use for everyone

Visit http://www.mppmu.mpg.de/bat for more info, updates, documentation, examples, etc.